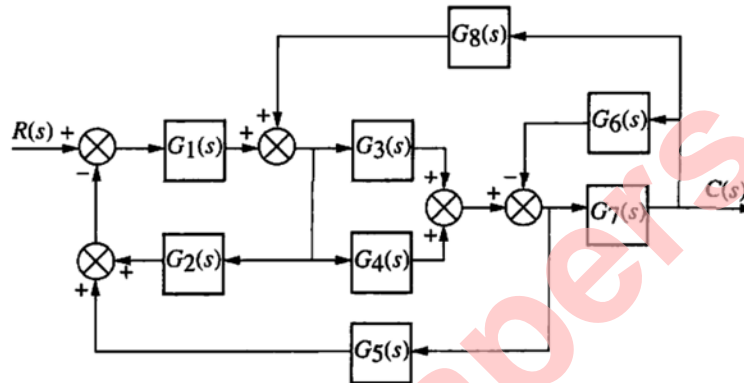


(3 Hours)

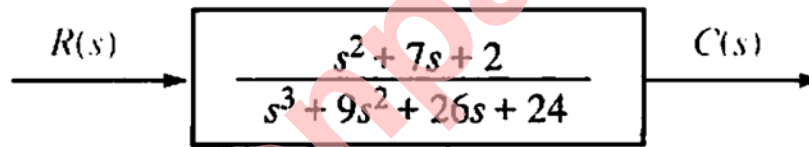
Total Marks : 80

- N.B. : (1) Attempt any **four** questions.  
 (2) Assumptions made should be **clearly** stated.  
 (3) Use log/semi – log paper is permitted.

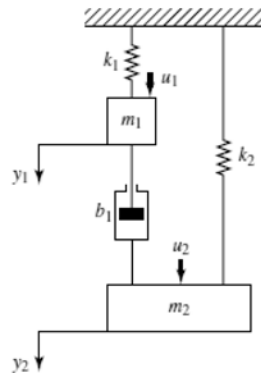
1. (a) Obtain the transfer function for the block diagram shown in figure below using block diagram reduction technique. 10



- (b) Find state - space representation of the transfer function shown below. 10



2. (a) Obtain a state-space representation of the mechanical system shown in figure below, where  $u_1$  and  $u_2$  are the inputs and  $y_1$  and  $y_2$  are the outputs. 10

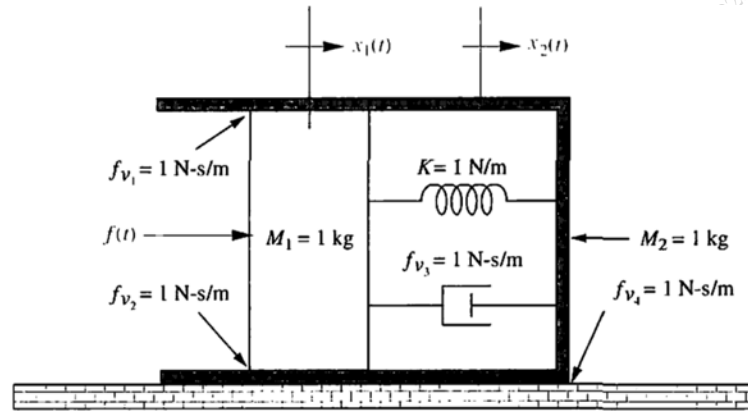


- (b) [1] Explain state of dynamic system, state variable, state space, state equation and output equation involved in state space modeling 05  
 [2] Distinguish between modern control theory and conventional control theory 05

3. (a) [1] Explain Lyapunov stability theory. 05  
 [2] Explain the common nonlinearities in control systems. 05

- (b) Find the transfer functions for the translational mechanical system shown in figure below. 10

TURN OVER



4. (a) For particular unity feedback system 10

$$G(s) = \frac{64(s+2)}{s(s+0.5)(s^2+3.2s+64)}$$

Sketch the bode plot. Determine the gain margin, phase margin, gain crossover frequency and phase crossover frequency. Comment on stability.

- (b) Write note on dynamic mathematical modeling of liquid level system having two tanks in series. 10

5. (a) For a unity feedback system the open loop transfer function is given by 10

$$G(s) = \frac{k}{s(s+2)(s^2+6s+25)}$$

Sketch the root locus and find the value of  $k$  at which system becomes unstable.

- (b) The open loop transfer function of a unity feedback system is given by 10

$$G(s) = \frac{k}{s(1+sT_1)(1+sT_2)}$$

Apply Routh – Hurwitz criterion, determine the value of  $k$  in terms of  $T_1$  and  $T_2$  for the system to be stable.

6. (a) For a certain control system 10

$$G(s)H(s) = \frac{K}{s(s+2)(s+10)}$$

Sketch the Nyquist plot and hence calculate the range of values of  $K$  for stability.

- (b) Determine the value of  $k$  such that the damping ratio  $\zeta$  is 0.5. Then obtain the rise time  $t_r$ , peak time  $t_p$ , maximum overshoot  $M_p$ , and settling time  $t_s$  in the unit-step response. 10

